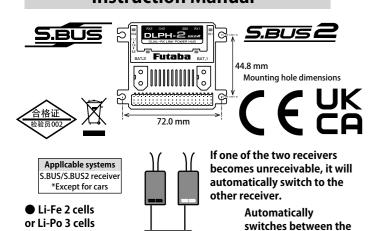
(Li-Po 3 cells)

Li-Po

# Futaba

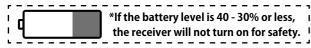
# **Dual RX Link Power HUB**

#### Instruction Manual



Up to 18 high-performance servos can be PWM connected.

DLPH-2



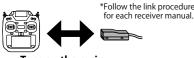
#### Receiver Link

1. Install two receivers on the aircraft as shown in the wiring diagram on the

**2.** Link the two receivers using the dual receiver feature of the transmitter. For systems without dual receiver capability, link each receiver in turn.

## Transmitter in link mode

For FASSTest 18CH Select dual mode and link primary







Turn on the sub receiver and link

Transmitter in link mode

mode and link secondary

For FASSTest 18CH Select dual

two batteries.

Li-Po

#### **◆** About telemetry system

When using the dual receiver function

The telemetry function of the main receiver

- can be used
- · Sub-receiver telemetry function is not available
- Other than dual receiver function
- Telemetry not available
- Set telemetry to INH (disabled)

### **Battery F/S**

- For receivers that can set the battery F / S, set the battery F / S to 4.8 V
- Also, make sure that the battery F / S of the two receivers have the same

Since the output voltage from DLPH-2 is 5 V, if the battery F / S is set to 5 V or higher, the battery F / S will alway operate.

#### Fail-safe

• If a receiver error occurs, priority is given to the output of RX1 (main receiver) for F/S data.

Thank you for purchasing the DLPH-2. Before using your new DLPH-2, please read this manual thoroughly and use the DLPH-2 properly and safely. After reading this manual, store it in a safe place

Use: Two receivers and two batteries communication switching device

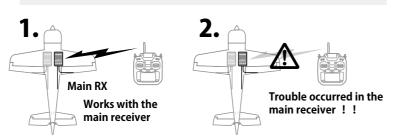
Size:  $62.8 \times 62.4 \times 18.1 \text{ mm}$  $(2.47 \times 2.46 \times 0.71 \text{ in})$ 

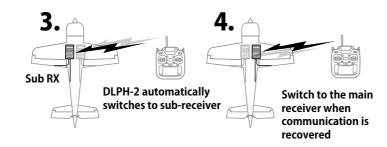
**Weight:** 50 g (1.76 oz)

FET rated: Always 60 A / 2 pcs Operating voltage: DC6.4 V to 13.0 V

**Accessories:** ● Switch ● Mini screwdriver ● Flange damper

■ Eyelet ■ Wood screw ■ Receiver connection cord x 3 (One cord is used in airplane gyro mode)



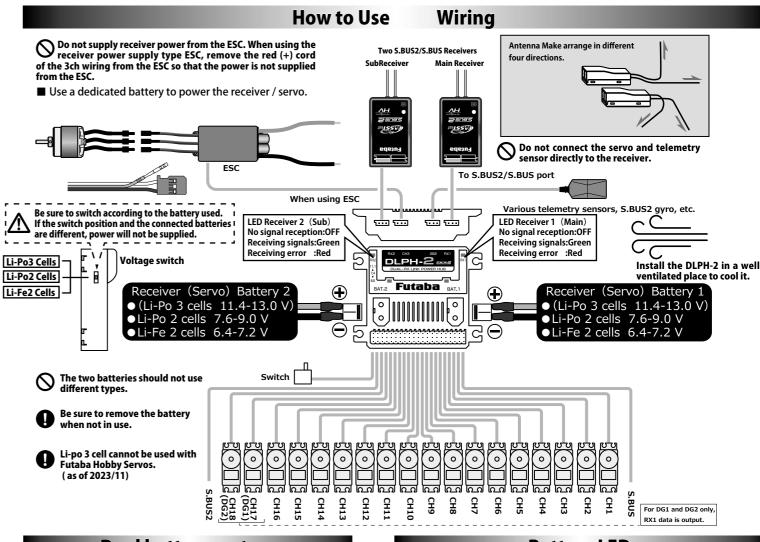


#### **Precautions**

#### **⚠ WARNING**

Failure to follow these safety precautions may result in severe injury to yourself and others.

- In order to prevent any short circuits, please observe the polarity of all
- Ensure that the unit is connected properly to the receiver.
- If the connector is disconnected during flight, it becomes inoperable.
- Ensure that the unit is mounted in an area that will eliminate exposure to
  - As with any electronic components, proper precautions are urged to prolong the life and increase the performance of the unit.
- Allow a slight amount of slack in the unit cables and fasten them at a suitable location to prevent any damage from vibration during flight.
- Be sure to link the two receivers with the transmitter.
  - It will not work unless the two receivers are linked. After startup, even if the link on one side is disconnected, the other side will continue to operate normally
- Used in a set of Futaba S.BUS / S.BUS2 systems.
- O Do not supply receiver power from the ESC. When using the receiver power supply type ESC, remove the red (+) cord of the 3ch wiring from the ESC so that the power is not supplied from the ESC.
- Use a dedicated battery to power the receiver / servo.
- O Do not connect the servo and telemetry sensor directly to the receiver.
- Large current flows through the Rx port of DLPH-2 and is damaged.
- O Do not connect a high voltage battery beyond the specifications of the servo used.
  - There is a risk of explosion, fire and damage.
- O Do not use more than 60A for a moment.
  - Reference: Although it depends on the servo used and flight style, acro flight with 15 HPS servos has been confirmed.
- ① To ensure that the DLPH-2 is functioning as desired, please test
  - Do not fly until inspection is complete.
- Before the flight, disconnect the wiring of the main receiver from the DLPH-2 that is operating normally, and check if the sub receiver alone can control it.
  - Check if the DLPH-2 switches.
- O Do not use the DLPH-2 with anything other than an R/C model.



## **Dual battery system**

Two power supply batteries can be connected to the DLPH-2. Power is supplied from the battery with the highest voltage. The operating time is the total time of the 2 batteries. For example, even if the voltage of one battery drops, power can be supplied from the other battery. Even one battery can be used, but safer flight is possible if 2

This receiver employs an electronic switching (current is controlled by an FET circuit) system. When the exclusive switch is set to ON or is nulled the power is turned on Switches other than the exclusive switch cannot be used. In addition, since a very small current flows even when the power is off, always disconnect the battery from the connector when the receiver is not in use.

One or 2 batteries can be connected. When 2 batteries are connected, the battery with the highest voltage is used. When only one battery is connected, always insulate the unused connector. The battery can be connected to either side.

Use batteries with sufficient capacity for the specifications and number of servo motors to be used.

Even if the voltage of one of the batteries drops, power is supplied from the other battery.

Even if the power supply wiring of one of the batteries breaks, power is supplied from the other battery.

When the switch is set to ON, power is supplied from the battery with the highest voltage. The operating time is the total time of the 2 batteries.

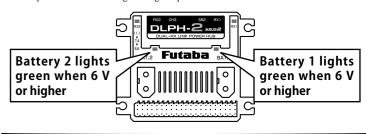
supplied from the battery which voltage is higher. Battery 2

Electric power will be

automatically and alternatively

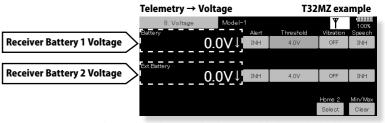
## **Battery LED**

The battery LED on the side being used lights up. It turns off when each becomes 6 V or less.



## Telemetry function (voltage display)

The DLPH-2 is equipped with a telemetry sensor function. The receiver voltage displayed on the transmitter home screen is only a constant value. The voltages of battery 1 and battery 2 should be monitored by telemetry voltage.



DLPH-2 uses two continuous slots. Please note that the proper default start slot for this accessory is number 6. When setup-changing or adding, it is the following numbers that are made to a start

#### 1,2,3,4,5,6,8,9,10,11,12,13,14,16,17,18,19,20,21,22,24,25,26,27,28,29,30

By connecting the transmitter and SB2 port, it is possible to register to the transmitter and change the start slot. In that case, it is necessary to connect the battery to DLPH-2 and supply power. Information on how to change the slot assignment is included in the transmitter's manual.

#### **FUTABA CORPORATION**

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#### Connection example for each application

S BUS.2

□ DG1, DG2.

Use the PWM output change

I Telemetry sensors cannot be

used in this mode.

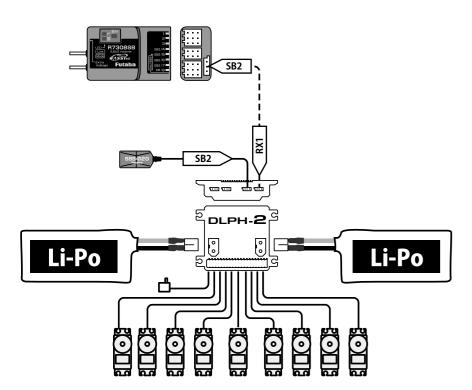
I mode of DLPH-2 as it is 1-16ch + I

Li-Po

#### Single receiver

#### Single receivermode

Connect the DLPH-2 to the compatible transmitter's S.I/F connector and change the mode.



This is an example of using one receiver and two batteries. Deal with battery problems. Since the dual RX function is not movable, it does not correspond to any reception troubles.

S.I/F port

#### Single receiver+Airplane gyro GYA553

#### Connect the DLPH-2 to the compatible transmitter's S.I/F connector and change the mode.

Single receivermode

I Do not connect servos I to GYA553. \*For GYA553 SB/R2 output switching, refer to the GYA553 instruction manual. (used in SB)

\*FASSTest26CH cannot be used when using GYA553. | DLPH-2 voltage sensor |

I cannot be used.

Li-Po 

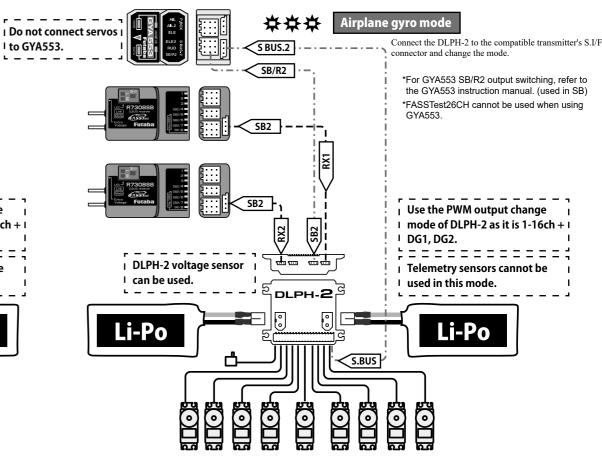
\*17-24ch+DG1,DG2

CH3→CH19

Here is an example using one receiver, two batteries, and an airplane gyro GYA553. Deal with battery problems. Since the dual RX function is not movable, it does not correspond to any reception troubles.

DLPH-2

## **Dual receiver+Airplane gyro GYA553**



Here is an example using 2 receivers, 2 batteries and an airplane gyro GYA553. Deal with battery problems. The dual RX function is activated to deal with any possible reception troubles.

## **DLPH-2 mode change**

The mode change of DLPH-2 is done by connecting to the S.I/F connector of the compatible transmitter. The setting method is described in the update manual of the compatible transmitter.

# **Compatible transmitter** Corresponding to the corresponding update RX1 port Futaba

Li-Po

DLPH-2.

Requires power supply to

Functions that can be changed with compatible transmitters

#### 1. Change setting mode

- Dual RX mode (default setting)
- Single receivermode
- Airplane gyro mode

#### 2. PWM output change

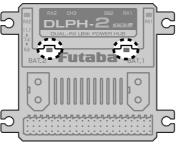
- 1-16ch+DG1,DG2 (default setting)
- 17-24ch+DG1,DG2 -

This PWM port can be changed from 1-16CH+DG1,DG2 (default setting) to 17-24CH+DG1,DG2.

\*9CH~16CH ports cannot be used.

When using single receiver + Airplane gyro GYA553 or airplane gyro mode, use 1-16ch + DG1, DG2 as they are.

### **Battery LED display at startup**



you of the current status of the DLPH-2.

# Both lit # 1 flashes: Dual RX mode 🗱 🗱 2 flashes: Single RX mode **☆ ☆** 3 flashes: Airplane gyro mode **Both lit** The battery LED display at startup informs

1 flashes: 1-16CH+DG1,DG2 mode 2 flashes: 17-24CH+DG1,DG2 mode



### **Battery LED**

The battery LED on the side being used lights up. It turns off when each becomes 6 V or less.

During this time, both LEDs will be lit regardless of battery voltage or number of connections.

To monitor the battery, check the LED display after this.